

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1134	600/424	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2007/02/19 14:09
S2	3	tracking same (object device implant) same (identify\$3) same projection same model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2007/02/19 14:14
S3	2	tracking and implant same (identify\$3) same projection same model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2007/02/19 14:15
S4	2	tracking and implant same (identify\$3) and projection near view and (3-d dimensional 3d) with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:08
S5	15	tracking and (implant object) and (identify\$3) with (feature object implant) and projection near view and (3-d dimensional 3d) with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 14:18
S6	4	tracking same (implant anatomy heart) and (identify\$3) with (feature object implant anatomy heart) and projection near view and (3-d dimensional 3d) with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 14:58
S7	200	tracking and (implant anatomy heart) and (identify\$3 determine locate measure) with (feature object implant anatomy heart) same (groove indentation angle) and (3-d dimensional 3d) with (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:18
S8	50	tracking with (implant anatomy heart) and (identify\$3 determine locate measure) with (feature object implant anatomy heart) same (groove indentation angle) and (3-d dimensional 3d) with (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 14:55

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S9	7	tracking with (implant anatomy heart) and (identify\$3 determine locate measure) with (feature object implant anatomy heart) same (groove indentation) and (3-d dimensional 3d) with (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:00
S10	210	tracking and (implant anatomy heart) and (identify\$3 determine locate measure) with (feature object implant anatomy bone femur) same (groove indentation angle) and (3-d dimensional 3d) with (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 14:54
S11	48	tracking with (implant anatomy heart) and (identify\$3 determine locate measure) with (feature object implant anatomy bone femur) same (groove indentation angle) and (3-d dimensional 3d) with (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:08
S12	2	tracking same (implant anatomy bone femur) and (identify\$3) with (feature object implant anatomy heart) and projection near view and (3-d dimensional 3d) with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:07
S13	0	"lloyd.in" and grimaud.in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:01
S14	0	"lloyd.in." and grimaud.in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:01
S15	25465	grimaud.in. Lloyd.in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:05
S16	62	Lloyd.in. and anatomy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:06
S17	3	grimaud.in. and anatomy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:06

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S18	48	tracking with (implant anatomy bone femur) and (identify\$3 determine locate measure) with (feature object implant anatomy bone femur) same (groove indentation angle) and (3-d dimensional 3d) with (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:15
S19	34	tracking with (bone femur) and (identify\$3 determine locate measure) with (feature object implant anatomy bone femur) same (groove indentation angle) and (3-d dimensional 3d) with (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:15
S20	178	tracking with (implant bone femur) and (identify\$3 determine locate measure) same (feature object implant anatomy groove angle indentation) and (3-d dimensional 3d) near2 (rendering model image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:23
S21	2	tracking with (implant bone femur) and (identify\$3 determine locate measure) same (feature object implant anatomy groove angle indentation) and (3-d dimensional 3d) near2 (rendering model image) and projection near view	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:26
S22	123	tracking with (implant bone femur) and (identify\$3 determine locate measure) same (feature object implant anatomy groove angle indentation) and (3-d dimensional 3d) near2 (rendering model image) and (projection near view (2d 2-d two near dimensional) with (image view))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 20:06
S23	103	tracking with (implant bone femur) and (identify\$3 determine locate measure charicteriz\$3) with (feature object implant anatomy groove angle indentation) and (3-d dimensional 3d) near2 (rendering model image) and (projection near view (2d 2-d two near dimensional) with (image view))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 15:34

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S24	103	tracking with (implant bone femur) and (identify\$3 determine locate measure characteriz\$3 characterization) with (feature object implant anatomy groove angle indentation) and (3-d dimensional 3d) near2 (rendering model image) and (projection near view (2d 2-d two near dimensional) with (image view))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 16:00
S25	50	tracking with (implant bone femur) and (identify\$3 determine locate measure characteriz\$3 characterization) with (feature object implant anatomy groove angle indentation) and (3-d dimensional 3d) near2 (rendering model) and (projection near view (2d 2-d two near dimensional) with (image view))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 16:17
S26	26	tracking with (implant bone femur) and (identify\$3 determine locate measure characteriz\$3 characterization) with (feature object implant anatomy groove angle indentation) and (3-d dimensional 3d) near2 (rendering model) same (projection near view (2d 2-d two near dimensional) with (image view))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 16:58
S27	2	("20020191814").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2007/02/19 16:59
S28	0	track\$3 with implant same (identify\$3 fiducial) same (deform\$3 deformation) and (3-d dimensional 3d) near model same (2-d 2d two near dimensional) near model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:11
S29	2	track\$3 with implant and (identify\$3 determine locate measure) same (feature object implant anatomy groove angle indentation) same (deform\$3 deformation) and (3-d dimensional 3d) near model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:12

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S30	0	track\$3 same implant and (identify\$3 determine locate measure characterize) with (deform\$3 deformation) same implant same (3-d dimensional 3d) near model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:13
S31	0	track\$3 same implant and (deform\$3 deformation) same implant same (3-d dimensional 3d) near model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:14
S32	2	track\$3 and implant and (deform\$3 deformation) same implant same (3-d dimensional 3d) near model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:14
S33	1928	implant with (deformation deform\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:15
S34	0	implant with (deformation deform\$3) same (3d 3-d dimensional) with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:15
S35	0	implant with (deformation deform\$3) same (3d 3-d dimensional) with (image rendering model)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:16
S36	46	implant with (deformation deform\$3) and (3d 3-d dimensional) with (image rendering model)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:19
S37	20	implant with (deformation deform\$3) and implant same (3d 3-d dimensional) with (image rendering model representation)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:25
S38	22	implant same (deformation deform\$3) and(3d 3-d dimensional) with (image rendering model representation) and fiducial	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:28

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S39	14	implant same (deformation deform\$3) and(3d 3-d dimensional) with (image rendering model representation) and fiducial and track\$2 and coordinate	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:41
S40	83	implant same (deformation deform\$3 registration register\$3) and (3d 3-d dimensional) with (image rendering model representation) and fiducial and track\$2 and coordinate	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 17:44
S41	31	implant same (deformation deform\$3 registration register\$3) same (3d 3-d dimensional) with (image rendering model representation) and fiducial and track\$2 and coordinate	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 18:04
S42	0	impant with track\$2 and implant same coordinate and (contour fiducial) same (measurement registration register\$3 locat\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 18:15
S43	0	impant with (navigation localization registration track\$2) and implant same coordinate and (contour fiducial) same (measurement registration register\$3 locat\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 18:07
S44	47	surgical with track\$2 and implant same coordinate and (contour fiducial) same (measurement registration register\$3 locat\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 18:19
S45	16	surgical with track\$2 and implant same coordinate and (contour fiducial) same (measurement registration register\$3 locat\$3) and implant with (3d 3-d dimensional) with (model rendering)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 19:01
S46	4	surgical with track\$2 and implant same (model and (ideal theoretical))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 19:05
S47	25	surgical with track\$2 and implant same (model and (ideal theoretical template))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 20:48

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S48	92	tracking and (implant bone femur) and tsai	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 20:07
S49	4	tracking and (implant bone femur) and tsai with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 20:09
S50	26	tracking and tsai with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 20:13
S51	18	tracking and tsai with projection	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 21:03
S52	2	"20040153191"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 20:48
S53	2	surgical with navigation and (theoretical ideal base) near model same compare same tracking	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 21:06
S54	2	surgical with navigation and (theoretical ideal base) with model same (evaluate update compare)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 21:06
S55	67	surgical with navigation and (theoretical ideal base) with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 21:10
S56	13	surgical with navigation and (theoretical ideal) with model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 21:11
S57	7	surgical with navigation and (theoretical ideal idealized) near2 model	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 21:13

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S58	6	surgical with navigation and compare with (model)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2007/02/19 21:13
S59	603	600/426	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2007/02/20 08:22
S60	1168	600/425	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2007/02/20 08:22
S61	21	(US-20050203384-\$ or US-20020150205-\$ or US-20020191814-\$ or US-20050080336-\$ or US-20040171924-\$ or US-20050143967-\$ or US-20020133264-\$ or US-20050134685-\$ or US-20060287612-\$ or US-20040179715-\$).did. or (US-7104996-\$ or US-7116330-\$ or US-6205411-\$ or US-6990220-\$ or US-6701174-\$ or US-6724915-\$ or US-6711432-\$ or US-5880976-\$ or US-5370698-\$ or US-5682886-\$). did. or (US-20040153191-\$).did.	US-PGPUB; USPAT; DERWENT	OR	OFF	2007/03/21 16:42
S62	0	S61 and closed with form	US-PGPUB; USPAT; DERWENT	OR	OFF	2007/03/21 16:43